



INNOVATION WITH HEART

MLX90900

Giving cobots a sense of touch
and a human-like perception

The **MLX90900**. A **tactile sensor** designed for cobots that could benefit the sense of touch. The sensor is **compact** and **lightweight** (6x6x5 mm³). Embedded in an elastomer, a magnet and 3D magnetometer integrated circuit (IC) work together using **Hall-effect technology** for **precise 3D force sensing**.

Fully integrated and mass-manufactured using cutting-edge semiconductor technology, the MLX90900 ensure accurate force measurements with **high sensitivity**, all while being **robust against stray fields** and harsh environments.

Let's give cobots a sense of touch, paving the way for safer, more efficient and accurate collaboration.

MLX90900 Tactile Sensor

The innovative Tactaxis™ technology

3D FORCE SENSING

Range:

- Normal force: 5N
- Shear force: 2N

Specifications:

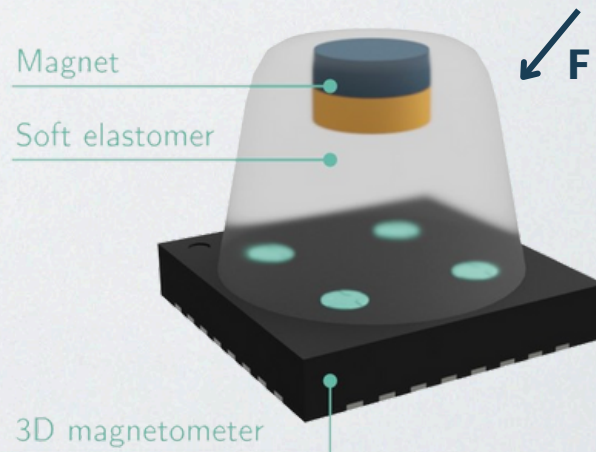
- Accuracy: 10% Full scale
- Precision: 1% Full scale
- Resolution: 10Nm

COST-EFFECTIVE

Compact and lightweight
6x6x5 mm³

Monolithic tactile sensor
(taxel)

Ease of mechanical
integration and electrical
interface



ROBUST

Stray magnetic field immunity
Thermal stability
Harsh environment ruggedness

MLX90900 Tactile Sensor

Melexis, a trusted partner



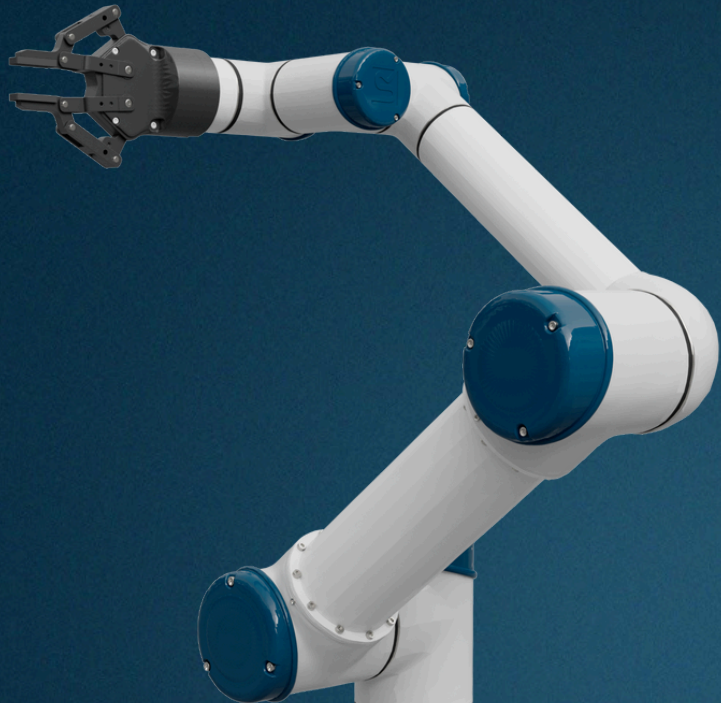
- Magnetic position sensor using 3D Hall-effect technology - Melexis' core expertise since 1994
- Ready for mass-manufacturing using state-of-the-art semiconductor and elastomer technologies
- Intellectual Property (IP): stray field rejection, slip detection algorithm, sensor integration

MLX90900 Tactile Sensor

Enablers for your cobots

- Handling fragile objects and performing delicate tasks
- Seamless, more efficient and safer interactions
- Market expansion unlocked





MLX90900 Tactile Sensor

Key features

- Slip and contact detection
- Force control
- Weight estimation

Applications

- Pick and place
- Assembling
- Handling
- Harvesting
- Gripping
- ...

CONTACT US

For any questions, partnerships or advanced projects, do not hesitate to contact our expert

Julien Ghaye



jug@melexis.com



References

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